Working with processed aircraft data

Bruno Piguet

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Plan

Working with data

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Introduction

AIDA

Files

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Hands on

The context

- AIDA
- exported files
- You work

Three different contexts :

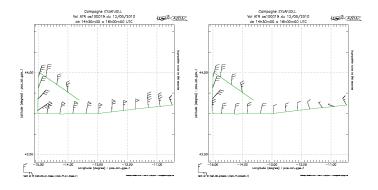
- Onboard aircraft : near-real-time. Automated processing.
- Quick-look : Fast. 1 Hz data. Automated processing. Simple to handle (one variable per measurement ("_comp_"))
- Processed data : Slow. Max sample rate. Human choices. Multiple versions. Iterations with PIs (versioning).

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Introduction AIDA Files

Difference between QL and processed data



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Introduction

AIDA

Files

Hands on

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Campaign's goal, for an operator :

Deliver qualified data to investigators

- General case : transfer files
- Specific needs : access to some visualisation tools.

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Introduction

AIDA

Files

working within AIDA

Why?

- Access to full dataset, at each processing step.
- Using existing tools.
- One workstation available

but

- needs some training
- a Unix/Linux thing
- Will not cover all your needs.

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Introduction

AIDA

Files

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AIDA in a few words

A very general freamework for the processing of time series.

- Metadata tied to data : autodocumented data format, automatic processing of metadata.
- One unique data format, whatever origins
- Simple storage : one directory/flight, one file per parameter + one per-flight metadata file.
- multiple-langages friendly : main processing library in C, but also labvie, Python, R, scilab.

Open framework (but you'll mostly meet AIDAGraph).

Used for QL and final processing.

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Introduction

AIDA

Files

Processing steps and variable naming

We divide variables in three groups :

raw ("quanta") : direct ouput from the machine. calibrated : automatic transformation of the above, in geophysical unit.

processed : intermediate or final version.

Raw data names are in CAPITALLETTERS Calibrated and processed variables use this naming scheme :

- A prefix : the family
- A postfix : the sample frequency
- in between : qualifiers, when needed : sensor, processing method. for calibrated variables : lower(raw_name) + "_cal"

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Introduction

AIDA

Files

parameters families

acc : acceleration alt : altitude att : attitude chm : chemical compounds ctl : control (houskeeping) lwc : liquid water hum : water vapour irf : refractive index mic : microphysique nav : navigation

pos : horizontal position prp : precipitation pre : (air) pressure ray : radiation tpr : temperature rft : time ven : wind vit : speed trb : turbulence flx : flux

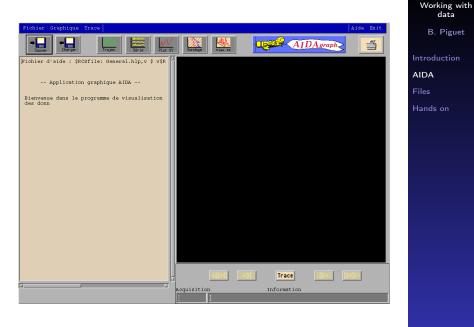
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Introduction

AIDA

Files



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Why work with these files?

- the real use-case in most campaigns
- origin-independant.
- using an already known tool

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Introduction

AIDA

Files

commonly availables

text NASA-AMES 1001 netcdf : two conventions (RAF & CF) .tur : Laboratoire aérologie (cf. Marie) "tasfile" : Simple text file, for some microphysics analysis

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Introduction

AIDA

Files

.kml : To show to your boss



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Introduction AIDA Files Hands on

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Text files

NASA-AMES 1001 Format Pros and con of text files :

- portable, but large.
- readable by humans ... not always (more than 2D), and risk of reduced resolution (0.0001 vs. 1.23456e-4)
- self-describing, but no universal glossary, nor dataset discovery mechanism.

We'll note :

- A family of formats (up to 4 dimensions, FFI)
- Simple structure (header, then text), giving ease of use (spreadsheet, various programming langages)

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Introduction

AIDA

Files

Basic NASA-Ames example

```
f = open(file_path)
NLHEAD, mark = f.readline().split()
NLHEAD = int (NLHEAD)
ONAME = f.readline()
# some more reading of the header
f.close()
```

```
M = np.loadtxt(file_path, skiprows=NLHEAD)
```

```
plt.plot(M[ :,3], M[ :,2])
plt.axis([3, 8, 51, 53])
plt.show()
```

Working with data

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Introduction

AIDA

Files

Hands on

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netcdf files

- binary format : close to the "true" representation.
- need specific software, but medata come for free.
- not afraid by large datasets
- more than one convention

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Introduction

AIDA

Files

```
What's available on local network ?

machine : lxtramm4 / 192.168.1.100, serves FTP, telnet

users : group_a to group_e

passwd : hyeres

data available at : $HOME/data_files

printer : trammlp2 / 192.168.1.10

wifi access :

SSID : equipe-tramm

WEP key : BD7FCAE784
```

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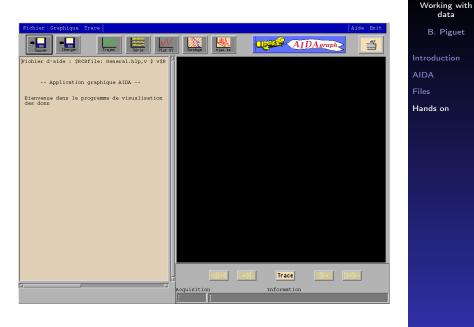
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Introduction

AIDA

Files

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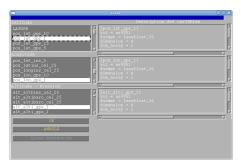
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Many GPS variables

```
-> choose pos_lat_gps_1, pos_lon_gps_1
```

! Be careful !

```
There are more than one definition of altitude!
```

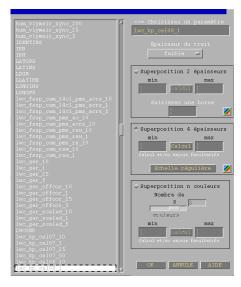
Working with data

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Introduction

AIDA

Files



Working with data

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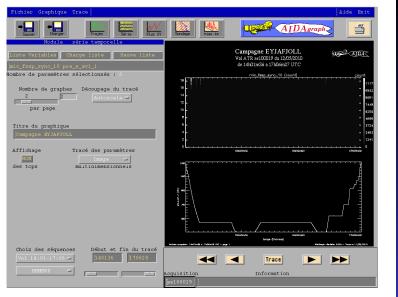
Introduction

AIDA

Files

Hands on

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Working with data

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Introduction

Files

Hands on

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Only synchronous variables !!

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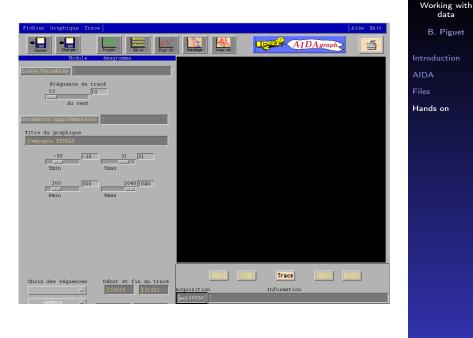
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Introduction

AIDA

Files

Hands <u>on</u>



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Température	Description des variab	les
tpr_arf_25 tpr_arf_50 tpr_arf_5 tpr_arf_10 tpr_art_10	/f][tpr_srt_1] vol = os0851 format = leeefloat_J2 dimension = 4 dim_array = 1	
lprin		
tpr_srd_10 tpr_srd_1 tpr_srd_200 tpr_srd_25 tpr_srd_50		
	FI	
hum_td_b_sync_10 hum_td_b_sync_1 hum_td_b_sync_25 hum_td_b_sync_5 hum_td_b_sync_val 1	[A] [[hum rd b sync_1] format = set0[5] format = leefloat_32 dimension = 4 dimension = 4	
pre_s_ar_1 pre_s_ar_200 pre_s_ar_2S pre_s_av1_10 pre_s_av1_1	<pre>[[pre_s_sv1_1] vol = ss051] dimension = 4 dimension = 4 dimension = 4</pre>	
	N. N	
ven_DO_pgps_1 %en_DO_pinsdat_1 ven_DO_pinsdat_25 ven_DO_pinsdat_5 ven_DO_pinsg_5	[1] [Ven_DD_pinsdat_1] vol = as0551 dimension = 4 dimension = 4	
	A	
ven_FF_pgps_1 Ven_FF_pinsdet_1 ven_FF_pinsdet_25 ven_FF_pinsdet_5 ven_FF_pinsg_5	<pre>[Iven_FF_pinedst_1 void = os0851 distant = leeefloat_32 dist_servy = 1</pre>	
ddrf Filtpage Affinê	OK ANNULE	AIDE

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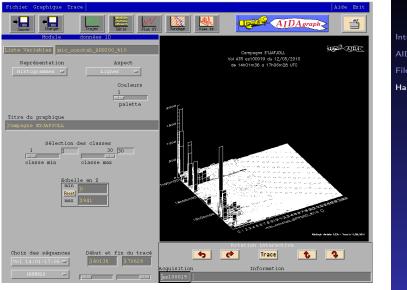
Introduction

AIDA

Files

Hands on

Many GPS variables
choose ven_DD_pinsdat_1, vent_FF_pinsdat_1 (or
ven_U_pinsdat_1, vent_V_pinsdat_1)



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Introduction

Files